## TRACKING DATA CALIBRATION



## Easily calibrate virtual tracking

		left 🔻	DFFSETS	
Camera 1 4 HEAD 3 LIFT	t t		X 0.102 Pan 0 Y 0.236 Tilt 0 Z 0 Roll 0	
		F	REE-D OUTPUTS	
Camera 1			BACKDROP Device Backdrop	
			Address 192.168.100.200 Port 4003	
	Y.			
		z		
			• RECORD	
			State State	HIM H
			An a set	

**multiCAM TRACKER** is an intuitive interface that compiles tracking data from different SPIRIT robotics to **generate a single Free-D signal per camera for virtual production engines**.

TRACKER is the simplest and most effective solution for using tracked robotics in a virtual environment.





The SPIRIT Slide, Dolly, Lift, and Head robotics systems are self-tracked, each delivering their XYZ and rotation motion data into space.

Because they can be combined into a "camera object," TRACKER handles signal aggregation to provide a single FreeD data to the virtual production engine.

Free-D is a standard used by the most common solutions: Backdrop, Disguise, Pixotope, Zero Density, etc...

## TRACKER

cunicia i				Y 0.2	
		ADD DEVICE	×		
		ROBOTICS PTZ TRACKER	FREI	E-D OUTPUTS	
			в	BACKDROP	
		SLIDER DOLLY LIFT HEAD			
		Free-D port 3003			
		∽ CANCEL ✓ CONFIRM			

Here is a concrete example with a Head / Lift / Dolly combination.

multiCA

	HEAD   LIFT   DO	LLY	
	Camera 1		
~	4 HEAD		
~	3 LIFT		
~	2 DOLLY		
~	1 Tracker Vive		



SPIRIT Robotic Solutions are used in various Virtual and Augmented Reality productions.

Contact us for a turnkey solution!



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multiCAM









## Contact us to receive our pricing list and live demo invites!

sales@multicam-systems.com

